GravitySpot: Guiding Users in Front of Public Displays Using On-Screen Visual Cues

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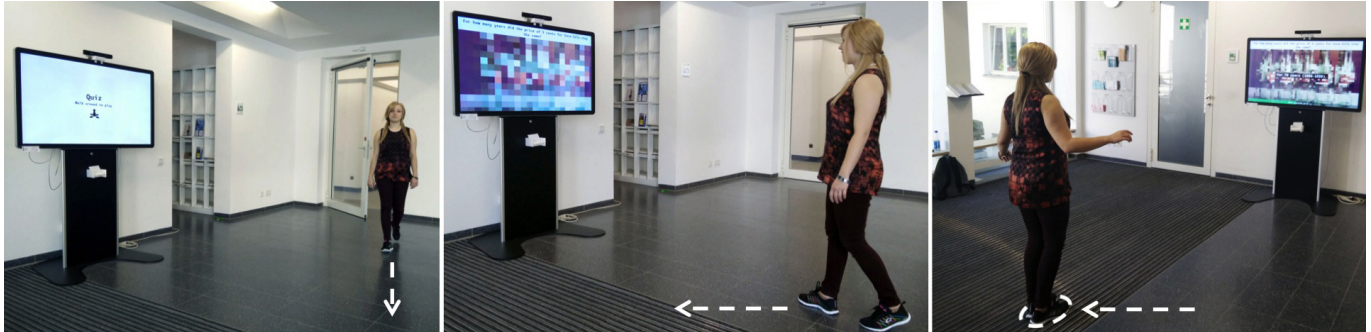Max Planck Institute for Informatics
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Figure 1. GravitySpot guides users towards designated positions in front of a display. We modify UI properties, such as brightness or resolution of images, depending on the user position. Thus we make passersby anticipate the spot where they can optimally perceive the content. In a sample application deployed in the wild, a trivia game is initiated as a user approaches the display (left). The answer is then provided as image which we modify based on user position (here pixelation, middle). As users move towards the sweet spot, the effect gets smaller until they can optimally perceive the image (right).

ABSTRACT

Users tend to position themselves in front of interactive public displays in such a way as to best perceive its content. Currently, this sweet spot is implicitly defined by display properties, content, the input modality, as well as space constraints in front of the display. We present *GravitySpot* – an approach that makes sweet spots flexible by actively guiding users to arbitrary target positions in front of displays using visual cues. Such guidance is beneficial, for example, if a particular input technology only works at a specific distance or if users should be guided towards a non-crowded area of a large display. In two controlled lab studies (n=29) we evaluate different visual cues based on color, shape, and motion, as well as position-to-cue mapping functions. We show that both the visual cues and mapping functions allow for fine-grained control over positioning speed and accuracy. Findings are complemented by observations from a 3-month real-world deployment.

Author Keywords
Public Displays; Interaction; Sweet Spot; Audience Behavior

ACM Classification Keywords
H.5.2 Information Interfaces and Presentation: User Interfaces—*Input devices and strategies*

INTRODUCTION

Displays have become ubiquitous in public spaces, such as shopping malls or transit areas in airports and train stations. At the same time, researchers and practitioners aim to increase suer uptake by providing interactive and engaging experiences [1]. This trend is further supported by sensing technologies (cameras, depth sensors, etc.) becoming available for easy and low cost integration with such displays. Sensing technology, however, has specific requirements regarding the optimal operating distance, thereby constraining the possible interaction space. For example, while touch sensors require the user to come in close proximity to the display, gestures-based interaction using Kinect allows users to position themselves freely between 0.5 m–4.0 m in front of the display. Stationary eye trackers require the user's head to be inside the tracking box – about 30 cm×30 cm – at a distance of 70 cm in front of the screen [26]. Hence, interactive displays face the challenge of how to encourage users to position themselves in a target location within the interaction space.

Similar challenges arise in situation where public displays are deployed opportunistically. Such deployments are often constrained by the size and layout of the physical space surrounding the intended target location [3]. This results in displays being positioned in non-optimal spots where, for example, users cannot easily stop without blocking the way of other passersby. This phenomenon has been coined the *butt-brush effect* [28]. In such cases, it would often be desirable to guide users towards less crowded areas, particularly in front of large displays. As a solution to these challenges, deployments aim to either anticipate the default sweet spot, i.e. the area where

users are most likely to stop as they approach the display, or they try to actively promote the optimal interaction area by means of explicit hints on the floor (footprints), next to the display (text), or on the display itself (text or silhouette).

We present *GravitySpot*, a novel approach that modifies the visual appearance of the display content based on user position. We leverage findings from human vision research that show that humans can very quickly process certain visual cues, such as color, motion, and shape. By showing the unmodified content only from a specific location in front of the display, users are made to anticipate this so-called sweet spot. *GravitySpot* advances the state of the art in several ways.

1. It allows for changing the sweet spot in an *adaptive and dynamic* manner, for example based on the current number and position of people in front of the display.
2. It does *not require attention switches* as cues are not decoupled from the actual screen content, in contrast to, for example, hints displayed on the floor or next to the screen.
3. It is more *robust against occlusions*, since by showing the cue on the screen, users can simply re-position themselves to perceive the cue, compared to cases, where other users are standing on a cue shown statically on the floor.
4. It neither requires space nor time-multiplexing between cue and content nor any overlays (e.g., silhouette) since it *integrates smoothly with the actual content*.
5. It requires *minimal hardware*. Any sensor that allows the user position to be determined can be used (e.g., Kinect).

We compare different visual cues with regard to positioning accuracy and speed and show how to improve them by adapting the mapping between user position and visual cue. We conduct two controlled lab studies (n=29). Results suggest a trade-off between accuracy and speed depending on the cue. In a second study we demonstrate that by altering the mapping between user position and cue intensity, this trade-off can be overcome and accuracy (up to +51%) and speed (up to +57%) be enhanced. This is valuable for designers, since it allows cues to be chosen based on the content shown on the display (for example, readability of text can be preserved by choosing appropriate cues). The studies are complemented with a real-world deployment. We show that also in a real-world situation, where users are unaware of how the cues work, they can quickly and accurately position themselves.

Our contribution is threefold. First, we introduce the idea of flexible sweet spots and propose a set of visual cues to guide users to arbitrary sweet spots in front of a display. Second, we present two controlled lab experiments to study the efficiency of the proposed cues and the impact of different mapping functions. Third, we present an in-the-wild deployment, demonstrating how to integrate the approach with an interactive application. We found that the approach is easily understandable to users with its efficiency being similar to the lab.

RELATED WORK

Our work builds on previous studies on (1) interaction models to influence audience behavior, (2) applications where interaction depends on or is influenced by a particular user location, as well as (3) positioning cues for public display applications.

Audience Behavior

Prior work investigated how people behave in the display vicinity and aimed to describe the process between the user being a passers-by until finally interacting. Spatial models [24, 30] describes different zones that define the interactions offered and the information shown on the display. These model often noticeably draw from Hall's theory of proxemics [14]. The public interaction flow model studies how groups socialize around public displays [9]. It identifies three activities – peripheral awareness, focal awareness, and direct interaction – as well as thresholds to be overcome by the user to proceed to the next phase. An extension of this model is the audience funnel, which attempts to model the probability of users transitioning between different phases of the interaction process [18]. The model distinguishes between a stage where users are simply passing by, followed by a stage where users are viewing and reacting. After this, subtle interactions (e.g. to find out how interaction works), direct interaction and eventually follow-up actions may occur.

All prior work has in common that it models important aspects in the interaction process in a spatial or temporal manner. At the same time, it is implicitly assumes that users are not only able to identify how interaction works but also to understand where they need to position themselves. Our work is based on the observation that attention is a crucial prerequisite for user positioning. Only after users notice the display it makes sense to focus on guidance. Our approach allows the stages defined in prior models to be refined by a positioning phase. This phase is not necessarily a part of the ultimate interaction step only but may span across multiple phases or zones. For example, positioning cues can already guide users before they notice that the display is interactive. Most closely related to our work is research by Koppel et al. [25] who showed that, by changing the display configuration, audience behavior could be altered, for example, how people approached, positioned, and interacted with the displays. Our method creates a similar effect but without the need to reconfigure the display, which is not feasible on-the-fly.

Location-Aware Display Deployments

A lot of display applications exist in which the interaction depends on the user location. Beyer et al. detect the user's position in front of a cylindrical display to let users draw a flower pattern on the screen [5]. GazeHorizon enables users to interact with the screen content based on gaze [35]. SpiderEyes is a toolkit for designing proximity-aware collaborative display applications [13], using the Kinect to determine the user's distance to the screen and adapt the content visualization accordingly. The Clavier is a walkable piano projected on a path [15]. A projection of the keyboard communicates the interaction area in which light sensors would detect user movements and then trigger auditory output. The Proxemic Peddler is an advertising display that makes the content adapt or move as users change their position [33]. The aim is to raise attention and foster (touch) interact with the content. Brudy et al. presented a system using the position of multiple users in front of a public display to increase privacy. One sample application they present is a spotlight that makes only areas of the screen visible that users obstruct with their body [10].
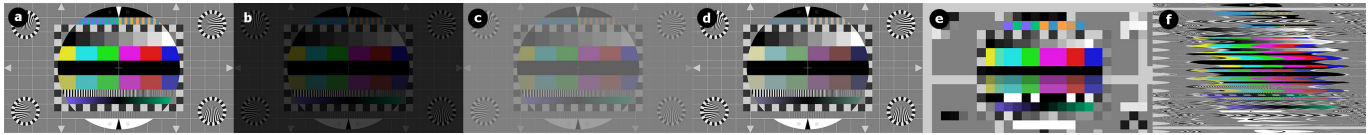
Figure 2. Visual cues investigated in this work (shown on a test pattern for intelligibility only): Original test pattern (a); color cues: brightness (b), contrast (c), and saturation (d); shape cues: pixelation (e) and distortion (f).

Users can also benefit from positioning in the context of visualizations on large wall displays. Ball et al. found increased physical navigation to improve user performance [4]. Further work found that in perception estimation tasks, users should position themselves at a certain distance and in a close-to-orthogonal angle to the display [7]. All aforementioned challenges can be addressed by the presented approach.

The variety of these applications shows that guiding the user in front of public displays can be beneficial in many ways. Whereas from a technology perspective a sensor may be limited to a narrow area in front of the display, users could also be guided towards less crowded areas in front of the display so they don't stand in the way of others or to increase privacy. We designed GravitySpot with these various application areas in mind, considering that visual cues for guiding the user should (1) not obscure the actual user interface, (2) be shown on the display itself in order not to be overlooked by users, (3) not require any attention switches, and (4) not be textual so as to minimize the cognitive load and be language-independent.

Positioning in Front of Public Displays

Beyer et al. showed that people tend to position themselves in a way so they can optimally perceive the content of a planar display and there is evidence that this also holds for non-planar display types [5]. As a result of this, sensors are usually placed so that they can best sense the user and their interaction. For example, the Kinect is usually placed below or above the screen [2, 19, 25, 29, 31] or cameras are placed above the display to sense the location [5, 6]. Some works employ very wide displays where one sensor cannot easily cover the entire interaction area. In such cases, several sensors are usually combined [29]. Beyer et al. later showed that frames on a (cylindrical) screen lead to users positioning themselves centrally in front of these frames [6]. This seems to work also in a subtle way since many of the users later could not recall the presence of frames. At the same time, this positioning cue (though it was not employed as such) only allows for a very coarse-grained positioning and overlays the user interface.

Few previous work studied means to influence user position in front of public displays. One recent work is GazeHorizon, an application that uses a webcam for gaze-based interaction with public displays [35]. To position users the authors used different cues, including floor labels, explicit on-screen distance information, and a mirror video feed overlaid with a face outline. While floor labels were usually overlooked by users, distance information worked better but required considerable time for correct positioning. In contrast, our work provides a thorough investigation and comparison of different positioning cues. Our cues can be employed to a user interface without obstructing any information and that can be constantly applied, leading to users staying in focus.

GUIDING USERS USING VISUAL CUES

Findings in cognitive psychology suggest that the human visual system can rapidly process a visual scene to extract low level features, such as color, shape, orientation, or movement, without the need to cognitively focus on them [27]. We aim to leverage this ability by mapping a user's current position to visual cues shown on the display.

Psychological Foundations

Our work exploits effects of attentive and pre-attentive visual perception, as introduced by Neisser [20] and confirmed by Treisman [27]. Neisser describes the process of visual perception as a two-step process. First, simple features of a scene are perceived, such as separating textures or the distinction between an object and its background (figure-ground perception). This stage is pre-attentive and characterized through parallel processing. It results in a set of features not yet associated with specific objects [17]. Second, users associate features to scenes, directing attention serially towards the different scene objects.

There is no consent in research literature as to which features are perceived pre-attentively [11]. There is strong evidence that the list of tasks working pre-attentively presented by Neisser is not conclusive. Hence, also the distinction between pre-attentive and non pre-attentive features is rather blurry. Research that aims to make this distinction includes the work from Wolfe [34]. He presents a list of 28 features, separated into likely, possible, and unlikely candidates for pre-attentive perception. As Wolfe noted himself, for many cases there is only little evidence since results stem from single publications – so the list may have to be extended in the future.

We base our research on the work of Nothdurft on the role of visual features during pre-attentive visual perception [21]. Nothdurft classified pre-attentive features into three categories: color, shape, and motion.

Selection of Visual Cues

We selected five visual cues according to Northdurft's categories (see Figure 2). According to Wolfe, all of these cues are likely to be perceived pre-attentively.

Color

Public displays often contain monochrome content, such as text. Hence, we opted for brightness and contrast as color cues, since these have a smaller impact on readability. To also consider features that affect the color information of multi-color content, we included saturation (see Figure 2b-d).

Shape

We selected shape features that alter the form of content and can be applied to content post-hoc. In particular we chose pixelation and distortion. While pixelation simply decreases the

resolution of the content, distortion applies a non-affine mapping function (see Figure 2e-f). Both cues have a strong impact on readability. Based on the font size, content becomes only readable near the sweet spot (10–20 cm).

Motion

Finally, as a motion cue, we opted for jitter that moves content with a frequency of 5 Hz along the screen axes. Based on the distance of the user from the sweet spot, the effect intensity is increased by adapting the motion amplitude.

Baseline

We compare these cues with two baselines from prior work. We opted for on-screen cues, since they were shown to work best in public settings [35]. The first cue is a compass-like arrow on the display that points to the direction in which users should move to reach the sweet spot. The arrow is slightly tilted in z-direction, indicating that "up" means moving forward. The second cue is a simple text telling users whether they should move 'forward', 'backward', 'left', or 'right'.

Apparatus

To evaluate how well users could be guided using visual cues we implemented the *GravitySpot* prototype. The C# prototype consists of (1) a tracking module that measures users' 2D position in realtime using Kinect and (2) a rendering module that allows any of the aforementioned visual cues to be applied to the display content. The intensity of the cue depends on the current distance of the user to the target position. We implemented different mappings (Figure 3), where the minimum is defined by the target spot and the maximum by the largest distance at which the user can still be sensed.

Sensor Calibration

We use the Kinect skeleton data to calculate the user position (x- and z-coordinate) in the 2D space in front of the display. To cover as much space as possible, we support the use of multiple Kinects – for example, with two Kinects a visual angle of up to 90° can be covered. We implemented a calibration tool that allows position information obtained from multiple Kinect sensors to be transformed into an x/z user position. For calibration we use triangulation based on 2 reference points.

To be able to change the sweet spot during runtime, our prototype allows a rectangular area to be defined within the field of view of the Kinect sensors. Arbitrary locations within this area can then be selected as sweet spots.

Mapping Between Position and Cue

During first tests, we noticed that the visual cues were subject to a trade-off between speed and accuracy of guiding a user to the sweet spot. To investigate this phenomenon in more detail we decided to implement different position-to-cue mapping functions. The functions were designed in such a way as to improve the visual cues so that the users find the sweet spot faster and/or more precisely. We chose four mapping functions (Figure 3): *Linear*, *SlowStart*, *QuickStart* and *SCurve*.

Linear mapping function. The linear mapping function was chosen as a baseline. The Euclidean distance x of the user is linearly mapped to the intensity of the visual cue.
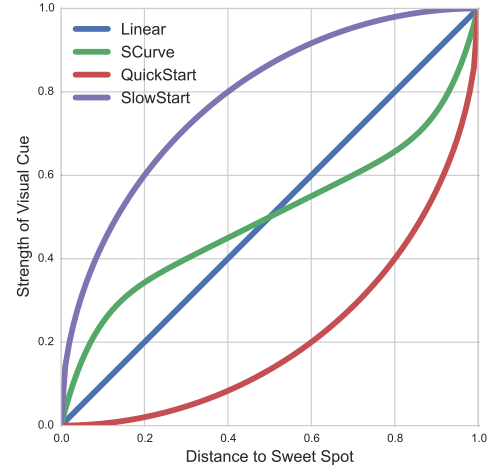
$$linear(x) = x$$

Figure 3. Position-to-cue mapping functions: While we hypothesize slow start to increase accuracy and quick start to increase speed, the S-curve was employed as a trade-off. A linear mapping was used as a baseline.

Slow start mapping function. We use a root function for the slow start mapping. At larger distances to the sweet spot, changes in user position cause only subtle visual changes. Changes become more obvious closer to the sweet spot. Thus, we expect that far away from the sweet spot, users need more time to figure out the direction in which to move, but then hit the sweet spot more precisely due to the increased change.

$$slowstart(x) = \sqrt{1 - (x - 1)^2}$$

Quick start mapping function. For the quick start mapping function, the most prominent changes to the visual cue happen at great distance to the sweet spot. We expect this function to guide the user early into the direction of the sweet spot and to improve task completion time. Since changes in position at smaller distances to the sweet spot only cause minor changes in the visual cue, we expect the accuracy to be low.

$$quickstart(x) = -\sqrt{1 - x^2} + 1$$

S-shaped mapping function. The s-shaped mapping function is a combination of the quick start and slow start mapping functions. We expect it to provide clearly visible changes at great distances and accurate feedback when the user draws near to the sweet spot. In the center span this function keeps a steady increase and does not fall flat. As a result, we avoid areas where the user receives no feedback on position changes. We expect this function to provide a good combination of speed and accuracy, while outperforming the linear function.

$$scurve(x) = \frac{(2(x - 0.5))^7 + 2(x - 0.5) + 2}{4}$$

Approach

To evaluate *GravitySpot* we designed three studies. In the first controlled laboratory study we compare the different cues with regard to positioning time and accuracy. Furthermore, we collect user feedback with respect to how easy it is for them to understand the different cues. The anticipated measures required a controlled setting where lighting was kept constant and where participants were able to approach the display from constant distances and angles. The study followed a repeated measures design.

In the second study we investigate the influence of the mapping functions that determine how the user position is mapped to the cue shown on the display. We are particularly interested whether positioning speed and accuracy could be further increased by applying the mapping functions. We also investigate whether the accuracy of fast cues can be increased and vice versa. We believe this to be valuable for designers who want to work with particular cues and show specific content. We selected two cues – brightness and pixelate – that users considered to work best in the first study.

As prior work showed user behavior to often differ in the real world as opposed to the lab [16, 19], we validated the ecologic validity of our findings through an in-the-wild deployment.

Applications
For the lab studies we needed an application that required users to position themselves precisely while timing measurements for a given task could be taken. For the in-the-wild deployment we needed an application that was engaging and easy-to-understand while at the same time requiring minimal interaction techniques, since these are in general very difficult to communicate in a public setting [31].

Spot-the-Difference
For the lab study we implemented a Spot-the-Difference game. In this game the screen shows computer-generated images of two shelves that contain a number of items in different colors. The position and color of the items on each shelf can be modified. The task of the user is to spot all items which differ between the right and left shelf. We do not allow any input, such as touching or pointing at the respective items. This is because measurements may be affected by the recognition accuracy of the system or users would be required to leave the sweet spot. Instead, users are asked to notify the experimenter verbally once they find the solution. The game was shown on a 78" projection screen with a resolution of 1600×1200 px.

Trivia Game
For the in-the-wild deployment we implemented a Trivia game (Figure 4) in which questions are shown on the display (55", LCD, 1600×1200 px) as soon as users enter the interactive area. Answers are shown in the form of still images to which the system applies the corresponding visual cue. A sample question could ask for the tallest building in the US and then show an image of the new World Trade Center in New York. Answers are shown as soon as users do not alter their position any more, assuming that at this point they reached the (subjective) current best position. We use a time-based threshold to decide when to display the answer, i.e. users have to stop for at least 1.5 s. Answers are shown for five seconds before the next question is displayed. For each question we make sure that the new sweet spot has a minimum distance to the old sweet spot, so that users need to alter their position.

LAB STUDY I: ACCURACY AND POSITIONING TIME
Participants
In total, 15 people (six female) participated in the study. Participants were students and employees with an average age of 23 years (std.dev.=2.8). Two participants owned a Kinect and seven wore glasses or contact lenses.

Figure 4. Trivia Game: Answers to questions are provided in the form of images. Only as users approach the sweet spot they can see the unmodified image and hence the answer to the question. As users remain in the sweet spot for some time we also display a textual answer before switching to the next question.

Stimulus and Task
As stimulus we used the Spot-the-Difference game. We selected five objects for the shelf – a pen, a shirt, a compass, a pile of books, and a briefcase. Five instances of each object were shown in different locations and colors (green, blue, red, yellow, purple). This way, we controlled for any potential effects caused by the shape or color only. For example, if we had only changed the position of two objects, the user would have been likely to spot the difference already at low contrast or brightness, whereas with the addition of color we ensured that users went as close to the intended sweet spot as possible.

Participants had to detect three differences in two images shown on the screen. To eliminate any side effect from participants trying to figure out what caused the visual changes, we told them beforehand that the visualization changes based on their position. We measured the duration between the user entering the Kinect's field of view – triggering the display of the stimulus – until participants notified the experimenter that they found the first difference. Participants had to explain their solution for verification. Note that we deliberately decided not to make finding the sweet spot the primary task, i.e. telling the user to find the spot where the image is optimally displayed. This way we created a task closely resembling a real-word situation and we avoided that users had to learn the "optimal" visualization. Thus, we can assume high internal and external validity, in particular regarding user feedback.

Experimental Setup and Procedure
We conducted the study in a room at our lab where we had set up the prototype consisting of two Microsoft Kinects and a wall-sized projection (see Figure 5). We marked two starting positions on the floor – one on the right side and one on the left side of the display at a distance of 5 m.

Upon arrival in the lab, participants were informed about the purpose of the study and asked to complete a questionnaire on demographics and experience with Kinect. We then proceeded with a series of vision tests, including a Snellen test
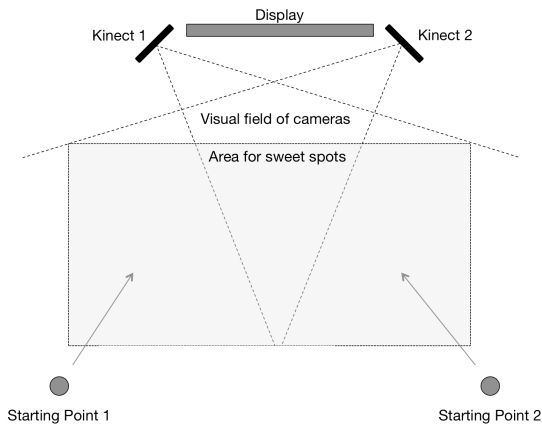
Figure 5. Setup for the lab study: participants started from two different starting points in alternating order. The sweet spot was randomly positioned within the visual field of view of the cameras.

[23] to measure visual acuity, an Ishihira test [8] to detect any form of color blindness, and a Pelli-Robson test [22] to assess contrast sensitivity. Only participants who passed all three tests were allowed to participate in the study.

We first asked participants to position themselves centrally in front of the screen and to play the game with no visual cue applied. We measured the time they needed to spot the first difference and repeated this task 5 times. The measurement allowed us to later correct the task completion time by the average search time of the participants.

We then tested the five visual cues and the two baseline cues. Each cue was tested in blocks of five repetitions. The block order was counter-balanced and the sweet spot was randomly positioned within the visual field of view of the cameras. For each repetition we changed the starting position (left or right) with the aim to cancel out any effect caused by ocular dominance [12]. After each block, participants were asked to fill in a brief questionnaire (5-Point Likert scale; 1=do not agree at all, 5=fully agree), assessing (1) how easy participants could recognize the relation between position and visualization, (2) whether changes in position where sufficiently accurate, and (3) whether changes in the visualization were easy to spot.

Results

Task Completion Times
We first analyzed mean task completion times per cue for each participant (see Figure 6–left). Greenhouse-Geisser corrected ANOVA found a significant main effect of visual cue ($F_{3.101,43.413}$=23.631, p<0.001).

We first compared our cues to the baselines: Bonferroni-corrected post-hoc tests revealed significantly shorter task completion times for contrast and saturate than for arrow (both p<0.05). Moreover, task completion times for jitter (p<0.005), brightness, contrast, and saturate (all p<0.001) were significantly shorter than for text. These results suggest that visual cues can significantly speed up guiding users to a defined sweet spot, compared to textual or symbolic cues.

Further differences were found between cues: distort and pixelate were significantly slower than the rest (distort vs jitter: p<0.005, distort vs rest: p<0.001; pixelate vs others:

p<0.01). Distort was not significantly different from pixelate, and all other visual cues also showed no significant differences between them. These results show the existence of two "groups" of visual cues with respect to task completion time: 1) slower ones (distort, pixelate), and 2) faster ones (brightness, contrast, jitter, saturate).

Positioning Accuracy
We analyzed mean euclidean distances to the sweet spot per cue for each participant (see Figure 6–right). Greenhouse-Geisser corrected ANOVA found a significant main effect of visual cue ($F_{3.356,43.623}$=36.333, p<0.001). Bonferroni-corrected post-hoc tests revealed that the differences between distort and the baselines were not significant (arrow: p=0.194, text: p=0.226). In contrast, all other cues showed significant differences to both baselines (all p<0.01).

Furthermore, distort and pixelate were not significantly different, but they were both significantly more accurate than all other cues (brightness: p<0.05, all others: p<0.005). Brightness was significantly more accurate compared to jitter (p<0.05), but not compared to saturate (p=0.241) and contrast (p=0.076). There were no significant differences between saturate, contrast and jitter.

In conclusion, similar to task completion times, this analysis revealed two main groups of visual cues, as can be also derived from users' trajectories (Figure 7): 1) More accurate ones (distort, pixelate), and 2) less accurate ones (saturate, contrast, jitter), with brightness as a compromise.

Questionnaire
In the following we analyze the questions users had to answer with regard to each cue during the study.

Correlation between position and visualization: There was a significant difference ($\chi^2(7)$=24.289, p=0.001) depending on the cue. Post-hoc tests revealed that jitter was ranked significantly worse than arrow, text, and brightness (all p<0.05). Arrow received the best median rank (2), followed by brightness and text (both 3). Jitter was ranked worst (7).

Accuracy of visualization: We found no significant difference depending on the cue ($\chi^2(7)$=10.378, p=0.168). Arrow, brightness, pixelate, and text were ranked with median 4. Distort/saturate received 5, followed by contrast (6) and jitter (7).

Changes in visualization: We discovered a significant effect for the cue ($\chi^2(7)$=30.000, p<0.001). Post-hoc tests revealed that jitter was ranked significantly worse than arrow, text, and pixelate (all p<0.05). Arrow and text received the best median rank (2), followed by pixelate (3), brightness (4), distort (5), contrast/saturate (6), and jitter (7).

Overall, jitter stands out: despite good performance with regard to task completion time it was perceived as less clear as the rest in all questions. From this we conclude that designers need to be particularly careful when applying this cue. Future work could further investigate this cue by (a) modifying the frequency of the movement and (b) applying this cue to particular objects rather than the entire screen.
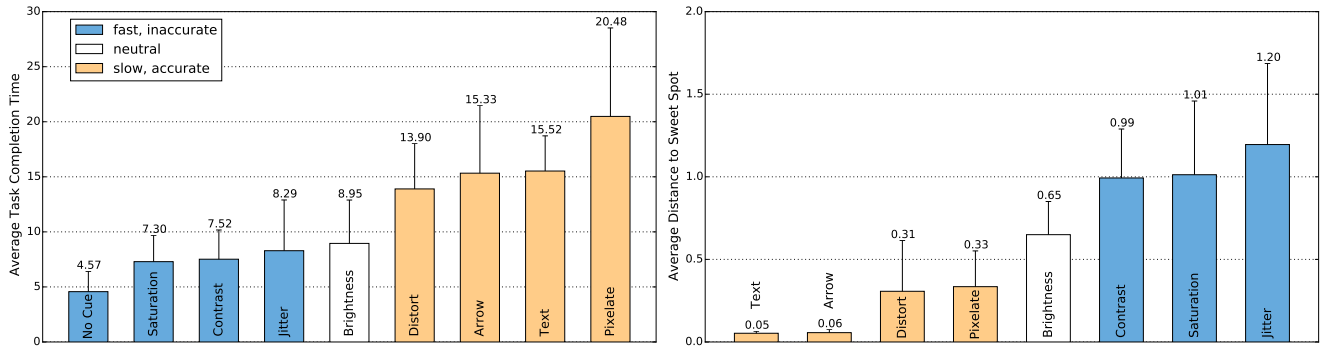
Figure 6. Average task completion time (left) and and accuracy (right). Our findings revealed two groups – slow but accurate cues (distort, pixelate), plotted in blue, and faster but less accurate cues (saturate, contrast, jitter), plotted in yellow. Brightness can be seen as a compromise between the two. 'No cue' represents users' average time to find the first difference.
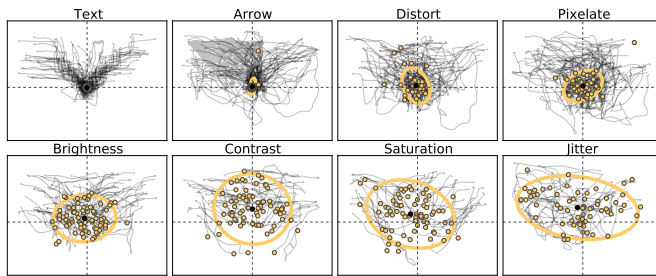

Figure 7. User trajectories (yellow dots: end points of trajectory; black dots: average of all end points per cue; yellow ellipse: covariance containing 95% of end points). The visualization shows which cues are more (baseline, pixelate, distort) and less accurate (contrast, saturate, jitter).

Conclusion

Our results show that visual cues differ significantly regarding guiding speed and accuracy. We revealed that these two aspects are opposed to each other, resulting in two groups: Slow but accurate guidances (distort, pixelate); and faster, less accurate cues (saturate, contrast, jitter). Brightness can be seen as a compromise. In consequence, we regard these cues as a flexible foundation to fit the different needs of deployments.

Next, we present two studies to further evaluate 1) fine-tuning with respect to guiding speed and accuracy, and 2) the cues' performances "in the wild".

LAB STUDY II: MAPPING FUNCTIONS

We were interested whether accuracy and/or task completion time could be further increased by using different mapping functions. This is potentially valuable information for a designer because it allows (1) a visual cue to be selected based on the specific positioning accuracy and task completion time required by the application and (2) a cue that preserves readability to be chosen. We selected two cues based on user ratings from the first study. To this end, we compared the four mapping functions for the pixelate and the brightness cue.

14 participants (six female) with an average age of 23.1 years (std.dev.=2.87) were recruited via mailing lists and Facebook.

Task, Setup and Procedure

As for the first study, we again used the Spot-the-Difference game to compare different mapping functions and we used the same setup depicted in Figure 5.

Participants had to complete the same pre-test and tasks and were provided the same instructions as in the first lab study. Again, time was measured until participants spotted the first difference. We began the study with a block of five repetitions were participants played the game with no visual cue applied. Then the eight conditions (2 cues×4 mapping functions) were presented in blocks with five repetitions in counter-balanced order. None of the subjects had participated in the first study.

Results

Task Completion Time

We analysed mean task completion times per cue and mapping per participant. Greenhouse-Geisser corrected ANOVA revealed significant main effects for cue ($F_{1,13}$=148.760, p<0.001), mapping ($F_{2.247,29.208}$=23.896, p<0.001), and cue × mapping ($F_{2.362,30.710}$=9.389, p<0.001). Bonferroni-corrected post-hoc tests showed that brightness led to significantly faster task completion times than pixelate (p<0.001), matching the findings from the first lab study. Regarding mappings, SCurve was not significantly different from linear, but all pairwise comparisons were significant (quick vs linear, slow vs linear, slow vs SCurve: p<0.05, all others: p<0.001).

The directions of the mappings' influences matched our expectations. QuickStart resulted in significantly shorter task completion times than linear, while SlowStart resulted in significantly longer ones. Hence, guiding speed can be significantly influenced by choosing different mappings. The results also suggest that speeding up adaptation has a larger influence on slower cues (QuickStart: +51% with pixelate, +7% with brightness), while slowing down is stronger for faster ones (SlowStart: -62% with brightness, -31% with pixelate).

Positioning Accuracy

As in the first lab study, we analyzed mean euclidean distances to the sweet spot per cue for each participant. Greenhouse-Geisser corrected ANOVA revealed significant main effects for cue ($F_{1,13}$=369.280, p<0.001), mapping ($F_{1.672,21.370}$=108.359, p<0.001), and cue × mapping ($F_{2.311,30.048}$=12.827, p<0.001). Bonferroni-corrected post-hoc tests revealed that brightness resulted in significantly lower accuracy than pixelate (p<0.001). This matches findings from the first lab lab. Comparing the mappings, we found no significant difference between linear and SCurve, but significant differences for all other comparisons (all p<0.001).
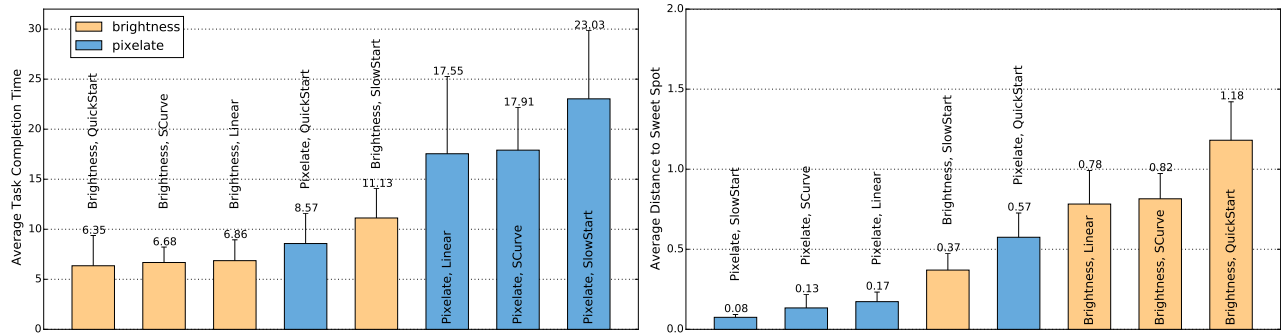
Figure 8. Average task completion time (left) and accuracy (right) in the second lab study. Note the two central cases in each figure, namely pixelate with QuickSart vs brightness with SlowStart: While brightness is generally faster than pixelate, the QuickStart mapping function was able to speed up pixelate to completion times similar to the brightness cue. On the other hand, pixelate is generally more accurate than brightness, but the SlowStart mapping function was able to improve accuracies of brightness to a level close to that of pixelate. These results show that mapping functions can be used to influence the speed-accuracy tradeoffs of the different cues.

Again, the directions of the influences fit our expectations: QuickStart resulted in significantly larger distances to the sweet spot than linear, SlowStart in significantly shorter distances. Thus, guiding accuracy can be significantly influenced by choosing different mapping functions. The results also suggest that speeding up adaptation has a larger influence on accurate cues (QuickStart: -232% accuracy with pixelate, -51% with brightness), while slowing down increases accuracy almost equally well for both more accurate and less accurate cues (SlowStart: +52% with brightness, 57% with pixelate).

Conclusion
Different mapping functions can be used to tweak desired visual cues towards either faster or more accurate guidance (Figure 8). In particular, faster adaptation leads to faster completion, but also increases final distances to the sweet spot. In contrast, slower adaptation guides users closer to the spot, but comes at the price of higher task completion times. In conclusion, we regard these mapping functions as a flexible toolset to tailor specific cues towards different needs for deployment.

REAL-WORLD DEPLOYMENT
We finally deployed the Trivia game in a public space to qualitatively and quantitatively assess the approach embedded with a playful public display application. In particular, we investigated how people behaved and how accurately users anticipated the sweet spot under non-controlled conditions.

Setup and Procedure
We deployed the Trivia game over 60 working days in a University building that hosts about 300 researchers from different disciplines (politics, sociology, communication science, computer science), a cafeteria, and several lecture theaters (see Figure 1). The display was deployed in the main foyer at a 90° angle to the normal walking direction of passers-by.

We used the most accurate cues (pixelate, distort, jitter) and selected SlowStart, QuickStart, and the SCurve (which yielded similar results as linear) as mapping functions. As a baseline, we selected arrows due to language independency and results similar to text. This resulted in ten experimental conditions (3 cues × 3 mappings + baseline). Conditions were randomly selected for each user. If users played subsequent games, the same cue was used.

Results
During the deployment 775 games were played in a total of 234 sessions. Overall, the most games were completed with pixelate (343), followed by distort (243). The least games were completed with baseline (121) and jitter (68).

Observations
To understand *how to best integrate the cues*, we tried different initial screen layouts during the deployment. In particular we compared showing the cue immediately as users entered the visual field of the camera to a screen that first explained the game to them. Showing the cue immediately led to more people interacting, since the motion caused by the movement seemed to attract the attention of passersby. We furthermore found that the different cues attract a user's *attention* to different extents. Cues that have stronger effects on the image (e.g., pixelation) seem to work better than more subtle cues (e.g., distort). This can be exploited by designers to attract more or less people to the display, for example based on the overall number of people in the vicinity or the application. Finally, cues seem to differ in *attractiveness*, reflected by how often people played in the different conditions. Pixelate had a quite immersive effect, leading to people playing on average more questions before leaving than for jitter, distortion, or arrow.

In general, observed numbers indicate that users preferred playing the game with the pixelate and distort cues. Most games (41) were completed for pixelate and SCurve mapping, and for distort and QuickStart (31). Over all mappings, Slow-Start led to fewer completed games (63) than QuickStart and SCurve (both 71). This suggests that slow initial adaptations may result in a less engaging / motivating gaming experience. Designers should thus base their decision for a particular mapping both on the required accuracy and application purpose.

Quantitative Findings
We focused on the accuracy of the different cues and mapping functions. We did not compare task completion times since we could not control for the time it took users to read and think about the questions. To account for the different sample sizes for the cues / mappings (see above) we report the following analyses / ANOVAs based on estimated marginal means (weighted means) instead of unweighted means, using SPSS.
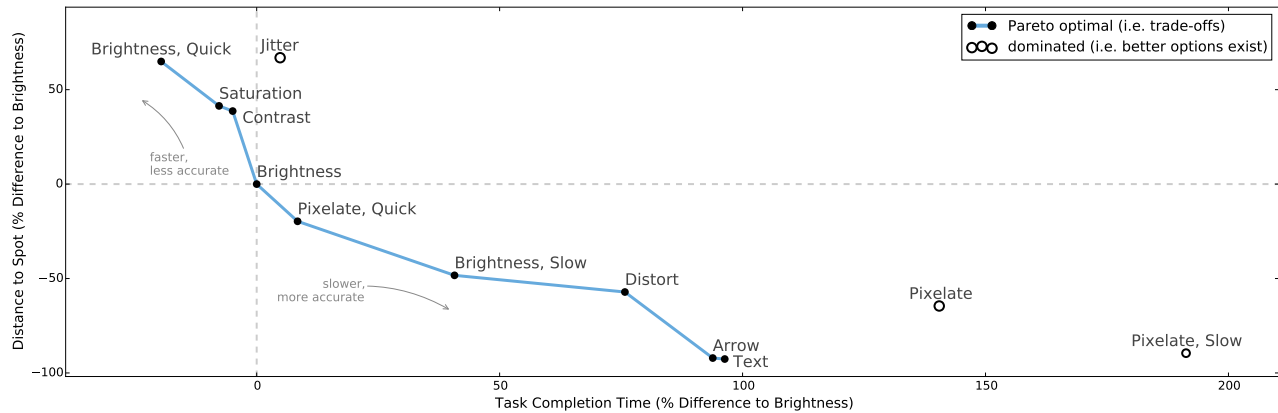
Figure 9. Trade-off chart for designers: Each point denotes a combination of mapping and cue on the speed-accuracy plane (combined lab study results). Bottom left is better (i.e. faster and more accurate). Data is scaled relative to the brightness/linear setup, which proved to be a rather neutral trade-off (see Figure 6). Filled circles along the trade-off front mark setups that are Pareto optimal, in other words there is no other setup that is better in both speed and accuracy. Hence, these setups provide different practicable speed-accuracy trade-offs. In contrast, empty circles mark dominated setups, meaning that other choices are better in both speed and accuracy.

Regarding accuracy we found no significant effect of cue ($F_{3,224}$=1.350, p>0.05). Averaged over all mappings, pixelate was most accurate (mean dist. 0.21 m), followed by distort, baseline (both 0.22 m), and jitter (0.25 m). We found a significant effect of mapping on distance ($F_{3,224}$=6.011, p<0.01). Averaged over all cues, SCurve (0.19 m) was more accurate than SlowStart (0.23 m) and QuickStart (0.25 m). The difference between QuickStart and the others was significant (Bonferroni-corrected post-hoc tests, p<0.05).

In summary, findings from our deployment confirm most results from the lab. In particular, the mapping functions can indeed enhance accuracy in the intended way. For example, accuracy in the deployment was on average 50% higher than in the first lab study with the standard mapping (e.g., pixelate – lab: 0.33 m, deployment: 0.21 m; distort – lab: 0.31 m, deployment: 0.22 m). Furthermore, differences in accuracy between cues are comparable for the lab and in-the-wild. From this we conclude that our approach is in fact capable of enabling interaction that requires accurate positioning of the user due to narrow interaction spaces, for example, eye tracking where users need to position themselves in a 30 cm × 30 cm area.

LIMITATIONS AND FUTURE WORK

First, we focused on single-user interaction. We configured our system to recognize and react to the first person to arrive. In future work, multiple users could be supported, which is beneficial for very large screens or screens employing multiple sensors and sweet spots. We believe the major challenge to be the relationship between cue and user. To make the relationship understandable for users, future work could investigate proximity or kinaesthetic matching. The latter approach is particularly promising since recent work showed that user representations on interactive public displays attract significantly more visual attention than other screen content [32].

Second, we only investigated playful applications. Yet the approach is in theory easily applicable to other applications, such as information displays. Text content may require further investigation, since some cues impact on readability. Optimal perception may require high accuracy, hence reducing speed.

Third, we employed our approach to the entire user interface, thus making it very prominent. Hence, we cannot draw any conclusion how well the approach works in situation where it is only applied to parts of the UI and where users may more easily oversee it. For example, an information display in an art gallery could provide textual information on an exhibit alongside with an image of the artist. Future work could investigate how well applying the cue only to the image works.

IMPLICATIONS FOR DESIGN

Our results show that designers can guide users with different cues, and that they should consider mapping functions to tune these cues with respect to speed and accuracy. Figure 9 summarises the resulting trade-offs, allowing designers to choose the setup that suits their needs best. Apart from accuracy and speed, cues should be considered regarding *readability*. For textual content, color cues seem more appropriate than shape-changing ones. In contrast, the latter seem to not only attract more *attention* (usually desirable for any public display app) but also to be more *entertaining and engaging* for users, making these cues particularly suitable for playful applications.

CONCLUSION

We presented *GravitySpot* – an approach to guide users in front of public displays using visual cues. The approach was evaluated in both lab and field experiments. The results suggest that the approach can ease the deployment of arbitrary kinds of sensors that have particular requirements regarding interaction distance but also allows the content and type of application to be considered.

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